= MATHEMATICAL MODELING =

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Simulation of Buffered Advection Diffusion of Calcium in a Hepatocyte Cell

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The calcium signaling is the basic and vital component of cell Abstract. communication in almost all types of human and animal cells. All the vital functions of parenchymal cell of liver known as hepatocyte cell are regulated by this calcium signaling. The calcium concentration at specific levels are responsible for each of the various functions of the cell. The deeper understanding of the mechanisms and the factors affecting the calcium dynamics in a hepatocyte cell is vital for various clinical applications related to diseases of the liver. In this paper, mathematical model is proposed to study intracellular calcium dynamics in hepatocyte cell by incorporating the processes like diffusion, advection, buffering etc. The reaction advection diffusion equation has been employed for a two dimensional unsteady state case, to form an initial and boundary value problem. The initial and boundary conditions are formulated based on the physical conditions of cell. Finite volume method and Crank Nicolson scheme have been employed along spatial and temporal dimension respectively to obtain numerical solution. The impact of endogenous and exogenous buffers, advection and diffusion on calcium dynamics in hepatocyte cell has been studied with the help of numerical results. The rise and fall in spatio-temporal calcium concentration in hepatocyte cell in response to specific conditions of advection, diffusion and buffer concentrations is observed. These variations in spatio-temporal calcium concentrations are regulated in narrow range due to fine coordination among these processes of cell under normal environmental and physiological conditions. The proposed model gives better understanding of interrelationship and interdependence of these physical processes for fine coordination among them to maintain structure and functions of cell.

Key words: hepatocyte cell, advection, diffusion, calcium, buffer, finite volume method.

INTRODUCTION

All vital functions of hepatocyte cell like glycogenolysis, production of proteins, contraction of bile canaliculi, apoptosis, cell cycle, the movement of lysosomes and other vesicles in cytoplasm are regulated by ionized calcium [1, 2]. The hepatocyte cell is cubical in shape and its internal calcium stores like endoplasmic reticulum are more denser in apical region of cell. The Ca²⁺ ions released from gate of calcium channel in cytoplasm undergoes different physical mechanisms like transportation and buffering etc. The calcium transport takes place by the combination of advection and diffusion in cytoplasm. The advection is the transport of Ca²⁺ ions by bulk motion due to pressure, viscosity, gravity etc. It causes the movement of calcium

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ions in cross flow direction. While the transport of Ca^{2+} ions due to concentration gradient is known as diffusion. Besides this transportion activity, calcium concentration is also controlled by buffering mechanism. About 99 % of calcium in cytoplasm binds with buffers to change their enzymatic properties [3, 4].



Fig. 1. Transport mechanisms in a hepatocyte cell.

It is evident from experimental investigation that calcium release always originates from specific region of the cell [1, 4]. The essential role of diffusion mechanism and buffers on the calcium dynamics is studied in cell with the help of mathematical model by M. S. Jafri [3]. The significance of numerical models to study biological processes involving diffusion and buffering is also discussed by past researchers [5]. The numerical study of calcium dynamics in the presence of excess buffer is reported in neuron cell [6, 7], fibroblast [8, 9], astrocyte [10, 11], oocyte [12], myocyte [13, 14] and hepatocyte cell [15] for one and two dimensional cases. The effect of calcium fluxes on spatio temporal variations of calcium concentration has been studied in neuron cell [16] and oocyte cell [17, 18]. Some attempts have been made to study the mechanics of calcium oscillations in pancreatic acinar cell [19, 20]. Very few attempts are reported for the study of one dimensional advection diffusion of calcium in astrocyte [21], myocyte [22] and oocyte [23]. No any attempt have been observed to study of buffered advection diffusion of calcium in hepatocyte cell. In this paper a mathematical model is derived to study combined effect of advection diffusion of calcium in the presence of different buffers in two dimensions. The results are obtained to study organization of calcium concentration with time, in presence of different buffers with different buffer concentrations, at different cross flow velocities and various values of diffusion coefficient of calcium in cytoplasm. In the primary part mathematical model with auxiliary conditions is derived to incorporate all mechanisms under consideration. Then finite volume method is implemented and simulated in MATLAB at different values of biophysical parameters. Obtained results are discussed in later part of paper.

MATHEMATICAL MODEL

Advection diffusion of calcium in a hepatocyte cell is governed by the principle of superposition. Total calcium flux in the cell is sum of diffusive and advective flux. The process of advection diffusion in presence of excess buffer is described by following expression [19, 20],

Rate of change of calcium concentration in hepatocyte cell = Diffusive flux + Advective flux + Buffer effect.

The partial differential equation involving diffusion, advection and buffering mechanism is given by [3, 24],

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$$\frac{\partial C}{\partial t} = D_C \left(\frac{\partial^2 C}{\partial x^2} + \frac{\partial^2 C}{\partial y^2} \right) - u \frac{\partial C}{\partial x} - k_j^+ [B_j]_\infty (C - C_\infty)$$

for

$$0 \le x \le 20, \quad 0 \le y \le 20, \quad t \ge 0,$$
 (1)

where C is cytosolic calcium concentration. $[B]_{\infty}$ excess buffer concentration given by $\frac{K[B]_T}{K+C_{\infty}}$, where $K = \frac{k_j^+}{k_j^-}$ is dissociation constant. The numerical values of biophysical parameters used for simulation are mentioned in Table 1 [3, 24].

Parameter	Description of parameter	Numerical value
D_C	Diffusion coefficient	100-200 $\mu m^2/S$
u	Advection velocity	10-20 μ m/s
C_{∞}	Stable calcium concentration	$0.1 \mu M$
k_j^+ for EGTA	Buffer association constant	$1.5 \mu M^{-1} S^{-1}$
K for EGTA	Dissociation constant	0.2µM
k_j^+ for Endogenous buffer	Buffer association constant	$50 \ \mu M^{-1} S^{-1}$
\overline{K} for Endogenous buffer	Dissociation constant	10µM
k_j^+ for BAPTA	Buffer association constant	$600 \ \mu M^{-1} S^{-1}$
K for BAPTA	Dissociation constant	$0.17 \mu M$
$[B]_T$	Total buffer concentration	$50-150 up\mu M$

Table 1. Numerical values of biophysical parameters

Auxiliary Conditions

The shape of hepatocyte cell is cubical, having sides of length approximately 20 μm each. The initial and boundary conditions can be framed by considering geometry of cell as follows.

Initial condition. Initially stable calcium concentration in hepatocyte cell is 0.1 μM [1]. Therefore, initial condition can be written as,

$$C_{t=0} = 0.1 \ \mu M, \quad for \quad 0 \le x \le 20, \quad 0 \le y \le 20, \quad t \ge 0.$$
 (2)

Boundary conditions. As the calcium is released from channels located on membrane of endoplasmic reticulum, which are very dense near apical surface of a hepatocyte cell [4, 25]. With this assumption, it is considered that calcium releasing channel is kept at $(0, 10) \mu m$ situated near midway of apical surface. Therefore by using Fick's law of diffusion the first boundary condition can be set as;

$$\lim_{x \to 0, y \to 10} -D_C \frac{\partial C}{\partial x} = \sigma_C \delta(x, y) \quad for \quad x = 0, \quad 0 \le y \le 20, \quad t \ge 0,$$
(3)

where, σ_C is influx of calcium from calcium channel and $\delta(x, y)$ is Dirac delta function sharply peaked at source kept at point (0,10).

On the remaining sides, other than the side having calcium channel of a hepatocyte cell, the calcium concentration attains its stable concentration $0.1 \ \mu M$. Therefore second boundary condition is framed along remaining sides of cells. It is assumed that, along remaining three sides calcium attains stable calcium concentration (C_{∞}) in a hepatocyte cell [4, 26].

$$C = C_{\infty} = 0.1 \,\mu M \tag{4}$$

along the three boundaries, $x = 20, 0 \le y \le 20 \ \mu m$, $y = 0, 0 \le x \le 20 \ \mu m$, and y = 20, $0 \le x \le 20 \ \mu m$.

SOLUTION

The first step of finite volume method is discretization of domain under consideration i.e. hepatocyte cell. In two dimensions hepatocyte cell (represented by square) is discretised as shown in Fig. 2, by using uniform grid having 81 nodal points. The hepatocyte cell is divided into 9 control volumes along each of the x and y direction. The horizontal and vertical distances between cell faces are denoted by δx and δy [27] equal to 2.5 μm each. The time step taken for numerical simulation is $\Delta t = 1 msec$.



Fig. 2. Two dimensional discretization of hepatocyte cell.

Equation (1) can be rearranged as,

$$\frac{1}{D_C}\frac{\partial C}{\partial t} = \frac{\partial^2 C}{\partial x^2} + \frac{\partial^2 C}{\partial y^2} - \frac{u}{D_C}\frac{\partial C}{\partial x} - \frac{k_j^+ [B_j]_\infty}{D_C} \left(C - C_\infty\right)$$
for $0 \le x \le 20, 0 \le y \le 20, t \ge 0$

$$(5)$$

It can be written as,

$$\frac{1}{D_C}\frac{\partial C}{\partial t} = \frac{\partial^2 C}{\partial x^2} + \frac{\partial^2 C}{\partial y^2} - a\frac{\partial C}{\partial x} - b\left(C - C_\infty\right)$$
for $0 \le x \le 20, 0 \le y \le 20, t \ge 0$

$$(6)$$

where, $a = \frac{u}{D_C}$ and $b = \frac{k_j^+ [B_j]_\infty}{D_C}$

Now to apply second step of finite volume method, i.e discretization of equation over a control volume, integrating Eq.(6) w. r. to time (t) and space (x) gives, [23]

$$\int_{t}^{t+\Delta t} \int_{x_{w}}^{x_{e}} \int_{y_{s}}^{y_{n}} \frac{1}{D_{C}} \frac{\partial C}{\partial t} dy dx dt = \int_{t}^{t+\Delta t} \int_{x_{w}}^{x_{e}} \int_{y_{s}}^{y_{n}} \left(\frac{\partial^{2} C}{\partial x^{2}} + \frac{\partial^{2} C}{\partial y^{2}} \right) dy dx dt$$

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$$-a\int_{t}^{t+\Delta t}\int_{x_{w}}^{x_{e}}\int_{y_{s}}^{y_{n}}\frac{\partial C}{\partial x}dydxdt - b\int_{t}^{t+\Delta t}\int_{x_{w}}^{x_{e}}\int_{y_{s}}^{y_{n}}\left(C-C_{\infty}\right)dydxdt$$
(7)

Solving space integration we get,

$$\frac{\delta x \delta y}{D_C} \int_t^{t+\Delta t} \frac{\partial C_G}{\partial t} dt = \int_t^{t+\Delta t} \left[\left(\frac{\partial C}{\partial x} \right)_{x_e} - \left(\frac{\partial C}{\partial x} \right)_{x_w} + \left(\frac{\partial C}{\partial y} \right)_{y_n} - \left(\frac{\partial C}{\partial y} \right)_{y_s} \right] dt - a \delta y \int_t^{t+\Delta t} [C_{x_e} - C_{x_w}] dt - b \delta x \delta y \int_t^{t+\Delta t} C_G dt + b C_\infty \delta x \delta y \Delta t$$
(8)

The weighted parameter θ is used to solve time integral.

$$\frac{\delta x \delta y}{D_C} [C_G - C_G^0] = \theta \left[\frac{C_E - C_G}{\delta x} - \frac{C_G - C_W}{\delta x} + \frac{C_N - C_G}{\delta y} - \frac{C_G - C_S}{\delta y} \right] \Delta t$$

$$+ (1 - \theta) \left[\frac{C_E^0 - C_G^0}{\delta x} - \frac{C_G^0 - C_W^0}{\delta x} + \frac{C_{N^0} - C_G^0}{\delta y} - \frac{C_G^0 - C_S^0}{\delta y} \right] \Delta t$$

$$- a \delta y \left\{ \theta \left[\frac{C_G + C_E}{2} - \frac{C_W + C_G}{2} \right] + (1 - \theta) \left[\frac{C_G^0 + C_E^0}{2} - \frac{C_G^0 + C_W^0}{2} \right] \right\} \Delta t$$

$$- b \delta x \delta y [\theta C_G - (1 - \theta) C_G^0] \Delta t + b \delta x \delta y \Delta t \qquad (9)$$

where θ lies between 0 to 1 and the values of coefficient at old time *t* are super scripted with 0. The eq.(9) can be rearrange in the following form,

$$\begin{bmatrix} \frac{\delta x \delta y}{D_C \Delta t} + \frac{\theta}{\delta x} + \frac{\theta}{\delta x} + \frac{\theta}{\delta y} + \frac{\theta}{\delta y} + a\theta \delta x \delta y \end{bmatrix} C_G = \\\begin{bmatrix} \frac{\delta x \delta y}{D_C \Delta t} - \frac{(1-\theta)}{\delta x} - \frac{(1-\theta)}{\delta x} - \frac{(1-\theta)}{\delta y} + \frac{(1-\theta)}{\delta y} - a(1-\theta)\delta x \delta y \end{bmatrix} C_G^0 \\ + \begin{bmatrix} \frac{\theta}{\delta x} - \frac{a\theta \delta y}{2} \end{bmatrix} C_E + \begin{bmatrix} \frac{\theta}{\delta x} + \frac{a\theta \delta y}{2} \end{bmatrix} C_W + \begin{bmatrix} \frac{\theta}{\delta y} \end{bmatrix} C_N + \begin{bmatrix} \frac{\theta}{\delta y} \end{bmatrix} C_S + \\\begin{bmatrix} \frac{(1-\theta)}{\delta x} - \frac{a(1-\theta)\delta y}{2} \end{bmatrix} C_E^0 + \begin{bmatrix} \frac{(1-\theta)}{\delta x} + \frac{a(1-\theta)\delta y}{2} \end{bmatrix} C_W^0 \\ + \begin{bmatrix} \frac{(1-\theta)}{\delta y} \end{bmatrix} C_N^0 + \begin{bmatrix} \frac{(1-\theta)}{\delta y} \end{bmatrix} C_S^0 + b\delta x \delta y$$
(10)

The Crank Nicolson scheme can be imposed by putting $\theta = 1/2$ in Eq.(10),

$$\begin{bmatrix} \frac{\delta x \delta y}{D_C \Delta t} + \frac{1}{2} \left(\frac{1}{\delta x} + \frac{1}{\delta x} + \frac{1}{\delta y} + \frac{1}{\delta y} \right) + \frac{1}{2} a \delta x \delta y \end{bmatrix} C_G$$

$$= \begin{bmatrix} \frac{\delta x \delta y}{D_C \Delta t} - \frac{1}{2} \left(\frac{1}{\delta x} + \frac{1}{\delta x} + \frac{1}{\delta y} + \frac{1}{\delta y} \right) - \frac{1}{2} a \delta x \delta y \end{bmatrix} C_G^0$$

$$+ \begin{bmatrix} \frac{1}{2\delta x} - \frac{a\delta y}{4} \end{bmatrix} C_E + \begin{bmatrix} \frac{1}{2\delta x} + \frac{a\delta y}{4} \end{bmatrix} C_W + \begin{bmatrix} \frac{1}{2\delta y} \end{bmatrix} C_N + \begin{bmatrix} \frac{1}{2\delta y} \end{bmatrix} C_S + \frac{1}{2\delta x} - \frac{a\delta y}{4} \end{bmatrix} C_E^0 + \begin{bmatrix} \frac{1}{2\delta x} + \frac{a\delta y}{4} \end{bmatrix} C_W^0 + \begin{bmatrix} \frac{1}{2\delta y} \end{bmatrix} C_N^0 + \begin{bmatrix} \frac{1}{2\delta y} \end{bmatrix} C_S^0 + \delta x \delta y$$
(11)

Eq.(11) can be put in the following form, for all internal nodes,

$$a_G C_G = a_G^0 C_G^0 + a_E C_E + a_W C_W + a_N C_N + a_S C_S + a_E C_E^0 + a_W C_W^0 + a_N C_N^0 + a_S C_S^0 + S_u$$
(12)

where,

$$a_{G} = \left[\frac{\delta x \delta y}{D_{C} \Delta t} + \frac{1}{2} \left(\frac{1}{\delta x} + \frac{1}{\delta x} + \frac{1}{\delta y} + \frac{1}{\delta y}\right) + \frac{1}{2} a \delta x \delta y\right]$$

$$a_{G}^{0} = \left[\frac{\delta x \delta y}{D_{C} \Delta t} - \frac{1}{2} \left(\frac{1}{\delta x} + \frac{1}{\delta x} + \frac{1}{\delta y} + \frac{1}{\delta y}\right) - \frac{1}{2} a \delta x \delta y\right]$$

$$a_{E} = \left[\frac{1}{2\delta x} - \frac{a \delta y}{4}\right]; a_{W} = \left[\frac{1}{2\delta x} + \frac{a \delta y}{4}\right]$$

$$a_{N} = a_{S} = \frac{1}{2\delta y}$$

$$S_{u} = b \delta x \delta y$$

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To incorporate first boundary condition at node 5, setting, $C_W = \sigma_C$

$$a_G C_G = a_G^0 C_G^0 + a_E C_E + a_N C_N + a_S C_S + a_E C_E^0 + a_N C_N^0 + a_S C_S^0 + S_u$$
(13)

where,

$$a_{G} = \left[\frac{\delta x \delta y}{D_{C} \Delta t} + \frac{1}{2} \left(\frac{1}{\delta x} + \frac{1}{\delta y} + \frac{1}{\delta y}\right) + \left(\frac{1}{\delta x} + \frac{1}{2} a \delta x \delta y\right)\right]$$
$$a_{G}^{0} = \left[\frac{\delta x \delta y}{D_{C} \Delta t} - \frac{1}{2} \left(\frac{1}{\delta x} + \frac{1}{\delta y} + \frac{1}{\delta y}\right) - \left(\frac{1}{\delta x} + \frac{1}{2} a \delta x \delta y\right)\right]$$
$$a_{E} = \left[\frac{1}{2\delta x} - \frac{a \delta y}{4}\right]; a_{N} = a_{S} = \frac{1}{2\delta y}$$
$$S_{u} = \left[\frac{2}{\delta x} + \frac{b}{2}\right] \mathbf{\sigma}_{C} + b \delta x \delta y$$

To incorporate second boundary condition at node 1, setting $C_{\infty} = 0.1$ and $a_W = a_S = 0$ we get,

$$a_G C_G = a_G^0 C_G^0 + a_E C_E + a_N C_N + a_E C_E^0 + a_N C_N^0 + S_u$$
(14)

where,

$$a_{G} = \left[\frac{\delta x \delta y}{D_{C} \Delta t} + \frac{1}{2} \left(\frac{1}{\delta x} + \frac{1}{\delta y}\right) + \left(\frac{1}{\delta x} + \frac{1}{\delta y} + \frac{1}{2} a \delta x \delta y\right)\right]$$

$$a_{G}^{0} = \left[\frac{\delta x \delta y}{D_{C} \Delta t} - \frac{1}{2} \left(\frac{1}{\delta x} + \frac{1}{\delta y}\right) - \left(\frac{1}{\delta x} + \frac{1}{\delta y} + \frac{1}{2} a \delta x \delta y\right)\right]$$

$$a_{E} = \left[\frac{1}{2\delta x} - \frac{a \delta y}{4}\right]; a_{N} = \frac{1}{2\delta y}$$

$$S_{u} = \left[\frac{2}{\delta x} + \frac{b}{2}\right] C_{B} + b \delta x \delta y$$

Similarly, second boundary condition can be incorporate at all boundary nodes, 1 to 73, 9 to 81, and 73 to 81. All equations obtained for each node forms the system of linear algebraic equations. Which can be expressed in matrix form as follows, for each time step;

$$[A]_{81\times81}[C]_{81\times1} = [B]_{81\times1}.$$
(15)

The Gauss elimination method is used to solve Eq.(15) at each time iteration to obtain solution vector $C_{81\times 1}$ by developing a MATLAB program.

RESULTS AND DISCUSSION



Fig. 3. The spatial variation of calcium profile in the presence of EGTA buffer.

The spatial variation of calcium in the presence of 50 μM EGTA buffer, with 10 $\mu m/sec$ cross flow velocity is shown in Fig. 3. The calcium concentration in hepatocyte cell at time t=0, 10, 50, 60 ms is plotted in subplots A, B, C, D respectively. Initially before opening the mouth

of calcium channel the calcium concentration is 0.1 μM . After opening the mouth of calcium channel nodal calcium concentration increases with time. The nodal calcium concentration becomes constant after t = 50 ms. Thus steady state concentration is achieved within 50 ms in the presence of 50 μM EGTA buffer and 10 $\mu m/sec$ cross flow velocity. The calcium concentration observed to be maximum at the mouth of calcium channel. It decreases sharply to attain stable concentration in remaining part of cell.

The effect of change in EGTA buffer concentration at constant cross flow velocity and diffusion coefficient is shown in Fig. 4. The calcium profile in a hepatocyte cell in the presence of 0, 50, 100 μ M EGTA buffer concentration is plotted in subplots A, B, C respectively. The nodal calcium concentration is maximum in absence of any kind of buffer. It is higher for lower values of buffer concentration. The buffer binds with free calcium ions as soon as they are released from mouth of calcium channel. This results in decrease in nodal calcium concentration away from the mouth of calcium channel.



Fig. 4. Spatial variation of calcium profile at different EGTA buffer concentrations and constant cross flow velocity in the hepatocyte cell.



Fig. 5. The effect of cross flow velocity on spatial calcium profile in the presence of EGTA buffer in the hepatocyte cell.

The calcium concentration in hepatocyte cell with cross flow velocity 0, 10, 20 $\mu m/s$ in the presence of 50 μM EGTA buffer is shown in subplots A, B and C of Fig. 5. respectively. We observed that the nodal concentration of calcium increases slightly with increase in cross flow velocity of calcium ions.



Fig. 6. The effect of cross flow velocity on temporal calcium profile in the presence of EGTA buffer.



Fig. 7. The effect of cross flow velocity on calcium profile in the presence of BAPTA buffer.



Fig. 8. The effect of cross flow velocity on calcium profile in the presence of endogenous buffer.

The effect of cross flow velocity on nodal concentration is shown in Fig. 6. The graphs are plotted at node 5, 14, 15, 25. The increase in calcium concentration is sharp in vicinity of mouth of channel. It decreases sharply away from channel mouth. The effect of increased cross flow velocity is observed high in the region nearby the channel. It decreases with distance away from the mouth of channel.

The effect of cross flow velocity on calcium concentration in the presence of BAPTA buffer is shown in Fig. 7. The minimum nodal calcium concentration is seen in the presence of BAPTA buffer. This is due to high binding capacity of BAPTA buffer. As soon as calcium is released from mouth of calcium channel BAPTA buffer binds with calcium ions with in very short period. This leads to decrease in nodal calcium concentration. The increase in cross cross flow velocity has not shown any substantial change on calcium profile in the presence of BAPTA buffer.

The effect of cross flow velocity on calcium concentration in the presence of endogenous buffer is shown in Fig. 8. The calcium profile with cross flow velocity 0, 10, 20 $\mu m/s$ is plotted in subplots A, B, C respectively. The calcium concentration increases slightly with increase in cross flow velocity in the presence of endogenous buffer.

The effect of change in value of diffusion coefficient of calcium in cytoplasm on calcium concentration is shown in Fig. 9. The calcium profile has been plotted by keeping constant cross flow velocity and constant EGTA buffer concentration with $DC = 100, 150, 200 \,\mu m^2/s$. It is observed that as diffusion coefficient increases, the calcium concentration decreases simultaneously. This is because the increase in diffusion coefficient causes increase in transport of calcium ions from source channel to basal part of cell leading to decrease in calcium concentration in the cell.



Fig. 9. The effect of diffusion coefficient on calcium profile in the presence of EGTA buffer.

CONCLUSION

The finite volume model is proposed and successfully implemented to study buffered advection diffusion in hepatocyte cell. The results obtained by simulation gives better insight of interrelationships among different physical transport mechanisms like, advection and diffusion in the presence of varieties of buffers. From the obtained results, it can be concluded that the advection mechanism greatly affects calcium concentration in the presence of EGTA buffer and endogenous buffer having small association rate constant, in the comparison with BAPTA buffer which has large association rate constant. The increase in cross flow velocity increases calcium concentration. While in contrast, increase in diffusion coefficient, decreases the calcium concentration in hepatocyte cell. Thus for high requirement of calcium concentration for specific activity, the advection mechanism is triggered by the cell to raise calcium concentration levels in the cell. Thereafter when activity is over the diffusion, buffering mechanism comes into play

to reduce the calcium concentration in the cell to acceptable tolerable limits of cell. The finite volume method is proved to be a versatile tool in the present study. The proposed model is able to provide us the patterns of different combinations of transport mechanisms leading to specific spatial and temporal calcium patterns which are results of fine tuning and coordination of three transport mechanisms in response to requirements of the specific activity of the cell. Such models can be developed further to generate the spatial and temporal patterns of calcium concentration in the cell formed by fine coordination among transport mechanisms in response to specific activity. The information generated from such models will be of great use to understand the fine coordination of processes in the cell and disturbance in these physical coordination leading to diseases of liver.

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